

# *Learning with Graphs*

## *A Gentle Introduction to Graph Neural Networks*

Dr. Pedro CASAS

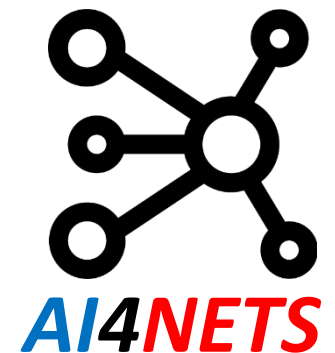
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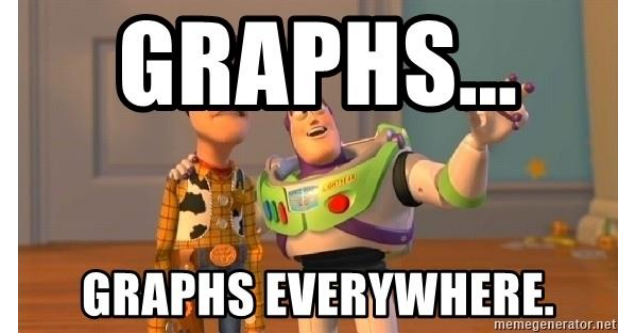
June 27, 2022

based on *ML with Graphs*, Jure Leskovec, Stanford University



# Learning with Graphs – Why Graphs?

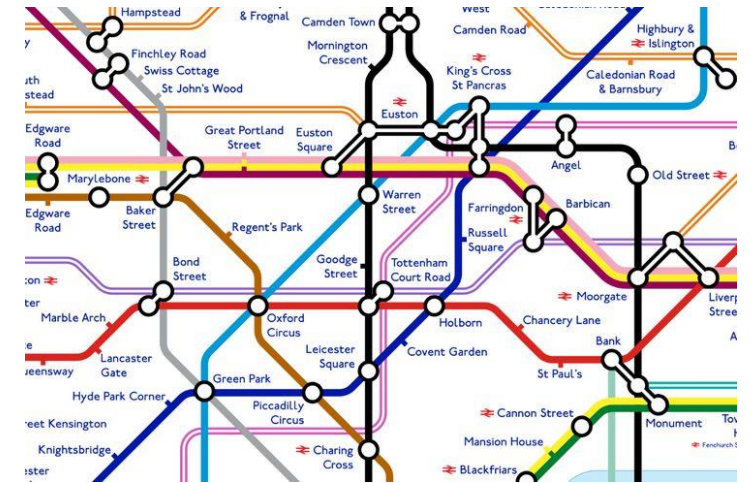
- *Graphs* are all around us
- Real world **objects are often defined** in terms of their **connections to other things**
- A **set of objects**, and the **connections between them**, are naturally expressed as a **graph**



*computer networks*



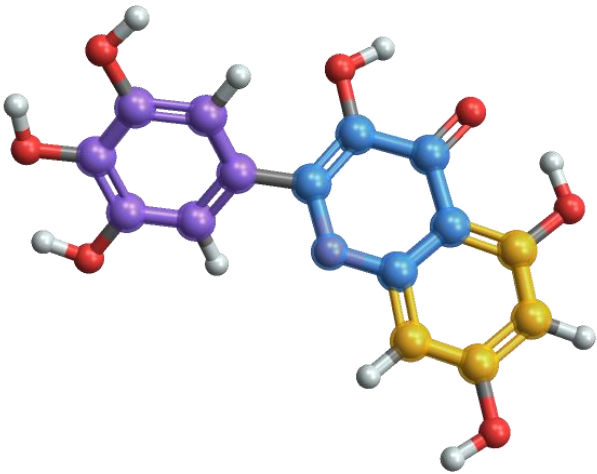
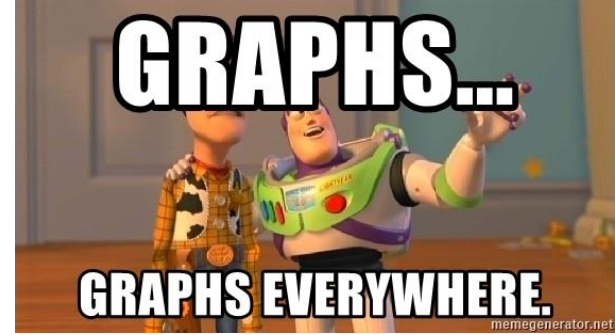
*social networks*



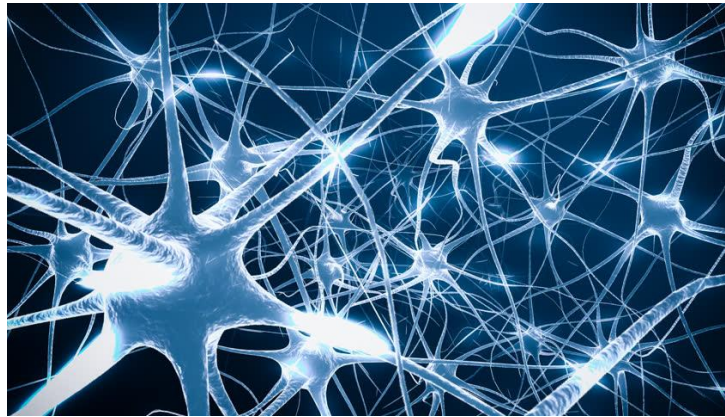
*transport networks*

# Learning with Graphs – Why Graphs?

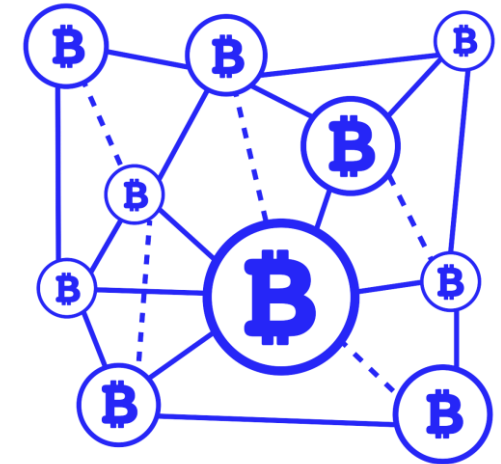
- *Graphs* are all around us
- Real world **objects are often defined** in terms of their **connections to other things**
- A **set of objects**, and the **connections between them**, are naturally expressed as a **graph**
- **Graphs** are a **general language** for **describing and analyzing entities with relations/interactions**



*molecules*



*networks of neurons*

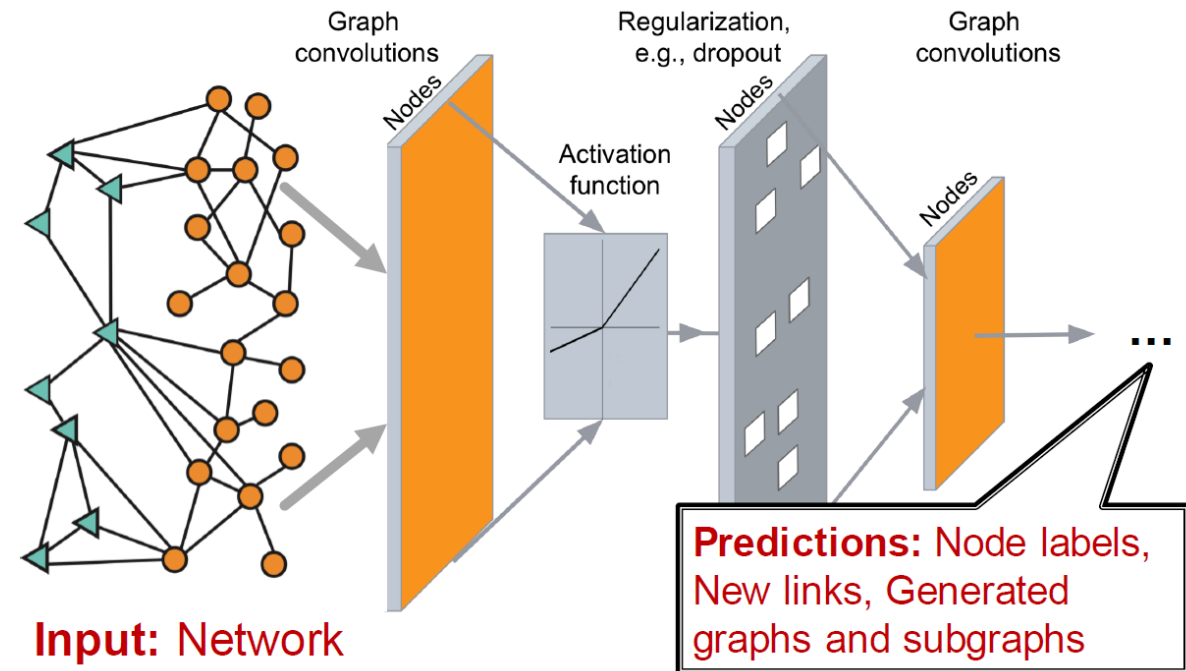


*transaction graphs*

# Learning with Graphs – How do we Use them?

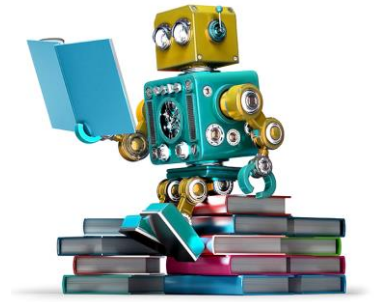


- **Complex domains** have a **rich relational structure**...
- ...which can be **represented as a relational graph**
- **Empirical results** – by explicitly **modeling relationships** we achieve **better performance**
- **Deep Learning in Graphs** – Graph Neural Networks (GNNs)
- Unique ability to learn and **generalize over graph-structured data...**
- ...enabled **groundbreaking applications** in fields where data are represented as graphs

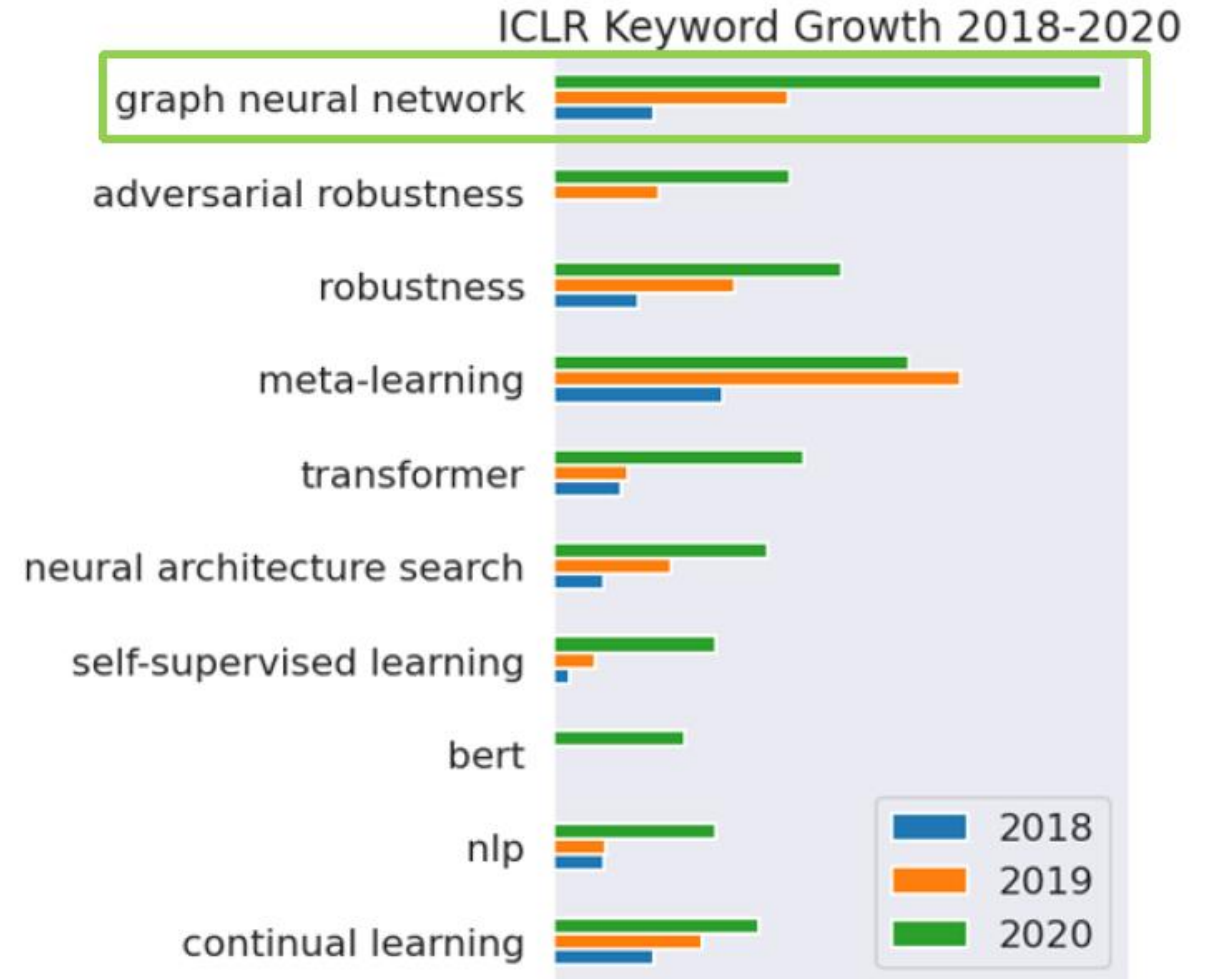
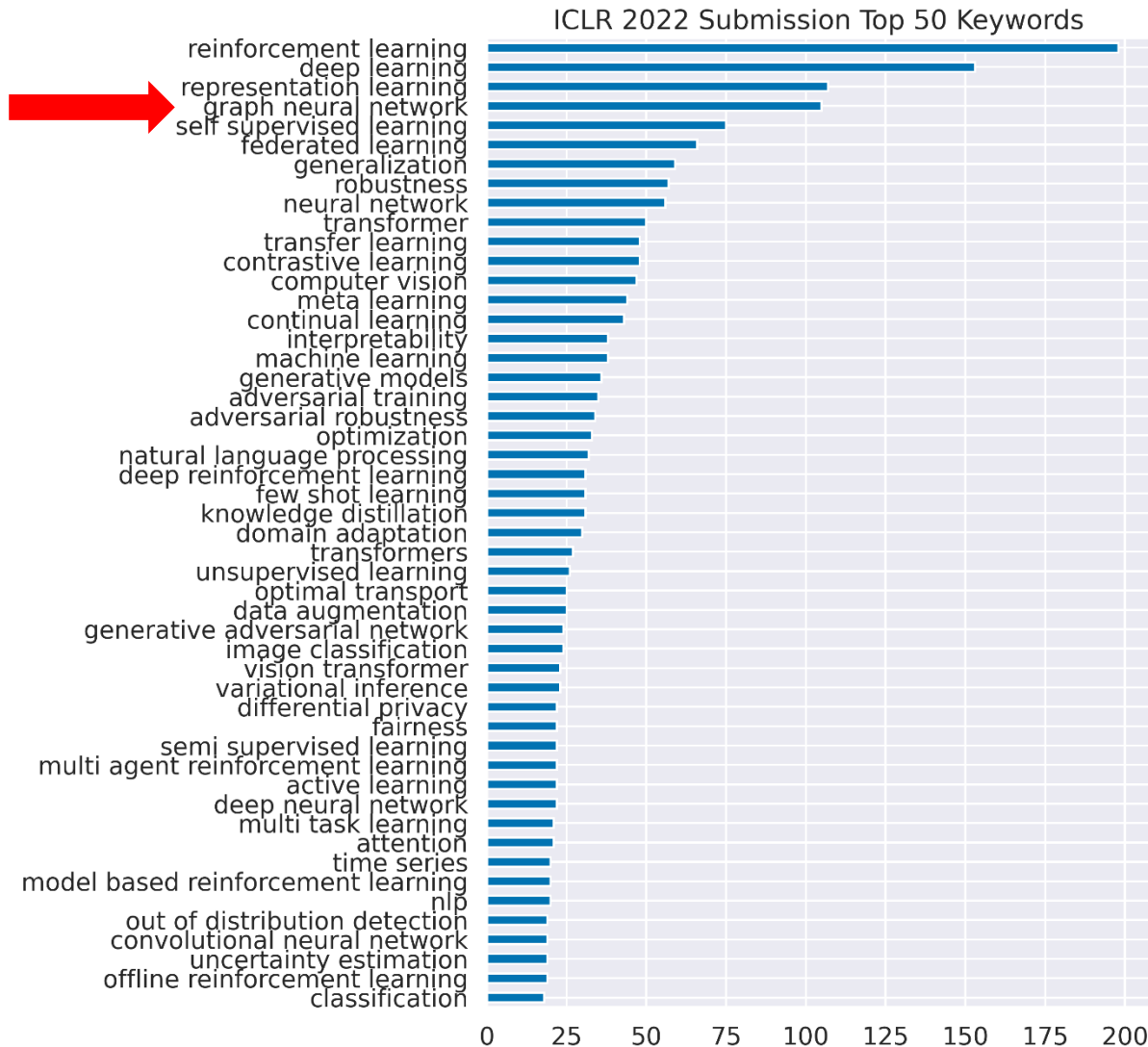




# GNNs are one of the *Hottest Sub-fields in ML Today*

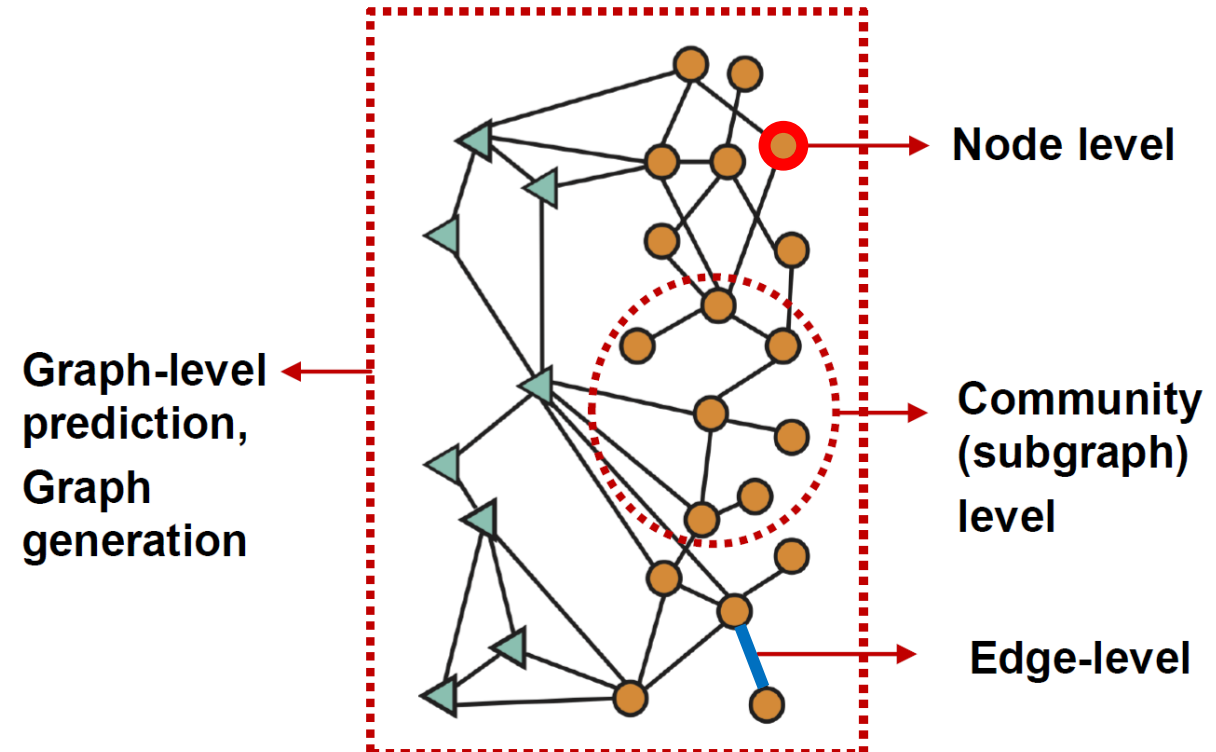
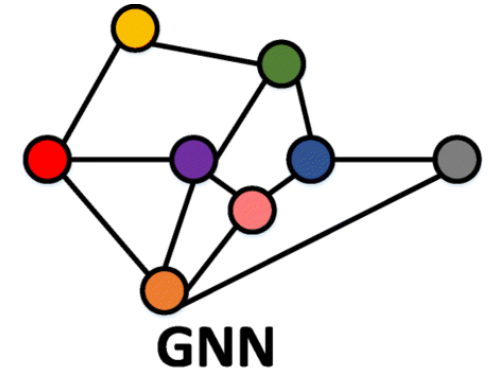


- **About 4% of ICLR 2022 submitted papers using GNNs**



# ***GNNs in a Nutshell – Classic Graph ML Tasks***

- **Graph Neural Networks (GNNs)** are a class of **deep learning methods** designed to **perform inference on data described by graphs**
- GNNs are **neural networks that can be directly applied to graphs** to tackle standard types of **tasks at the node-level**, **edge-level**, and **graph-level**
- We define a graph  $G(V,E)$ 
  - $V$  is the set of  **$n$  nodes** or **vertices**
  - $E$  is the set of **links** or **edges**
- Adjacency matrix  $A$  with dimensions  **$(n \times n)$**
- Matrix of node features  $X \in \mathbb{R}^{(n \times m)}$
- **Many types of graphs:** directed, undirected, bipartite, weighted, heterogeneous, etc.



# ***GNNs in a Nutshell – Examples of Tasks on Graphs***

- ***Node Classification***

- ***predict a type (label) of a given node***, by looking at the labels of the neighbors
- usually trained in a semi-supervised way, with only a part of the graph being labeled
- E.g., predict amino-acid sequences (e.g., ***DeepMind's AlphaFold***)

- ***Link Prediction***

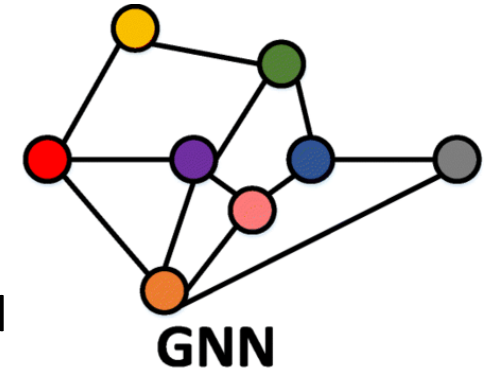
- understand the relationship between nodes in graphs
- ***predict whether there is a connection between two nodes***
- E.g., infer social interactions in social networks, recommendation systems

- ***Graph Classification and Prediction***

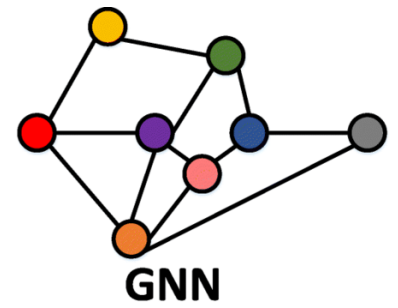
- ***classify the complete graph into different categories***
- similar problems to image classification
- E.g., molecule property prediction (protein is an enzyme or not), social analysis, Travel Time Estimation (e.g., ***Google Maps***)

- ***Graph Clustering***

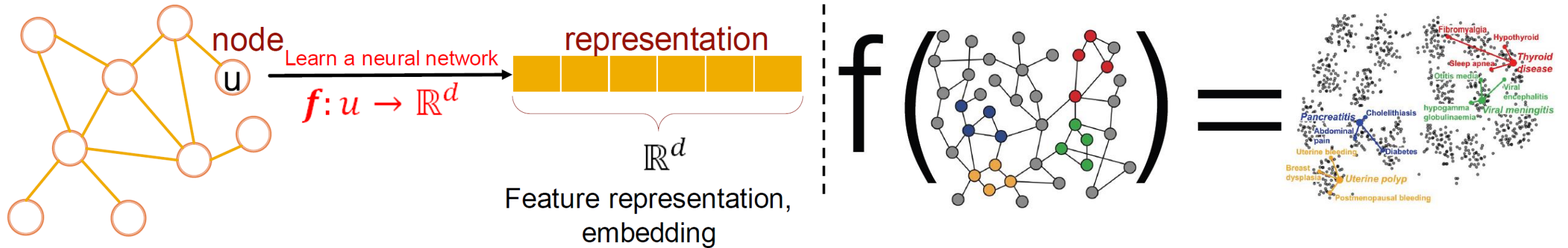
- detect if nodes form a certain community
- vertex clustering, graph clustering (similarity between graphs)
- E.g., identification of communities, anomaly detection



# GNNs in a Nutshell – Node Embeddings



- How do we **learn on graphs?** → (deep) **embeddings**
- The notion of **node embeddings**: map nodes to  $d$ -dimensional embeddings such that similar nodes in the network are embedded close together

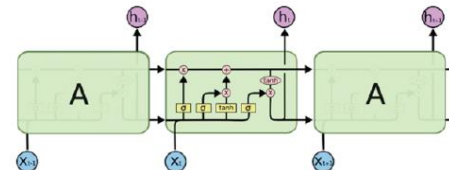
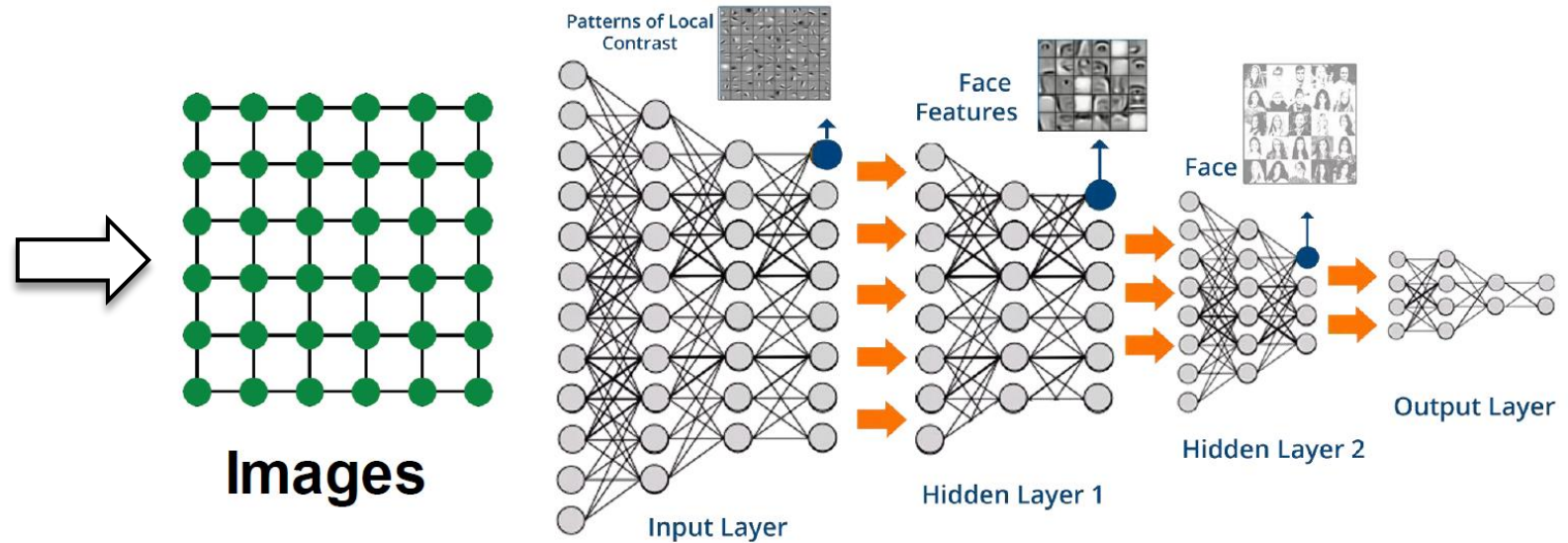
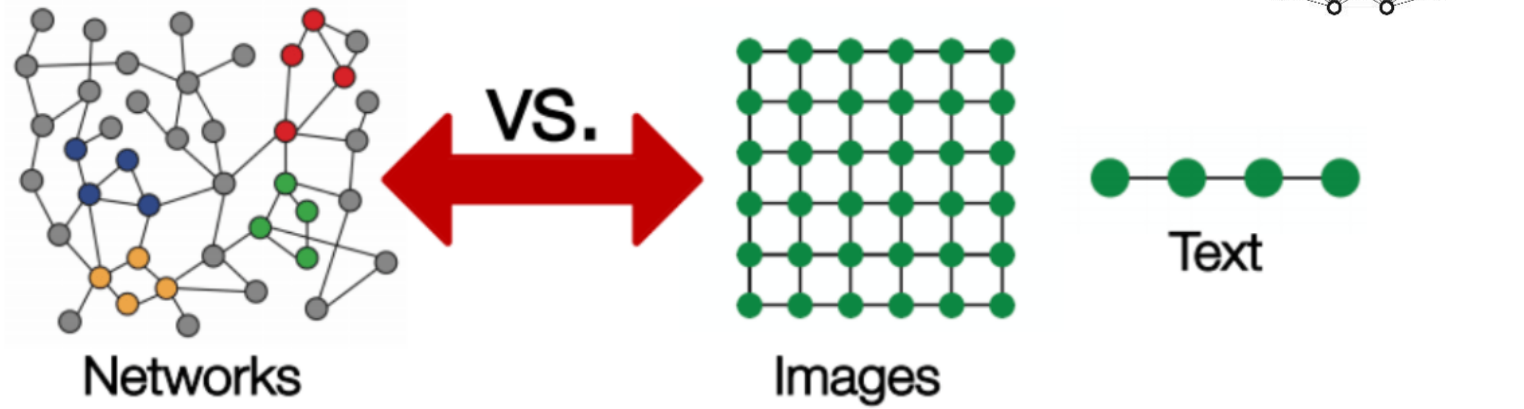


- The exercise is therefore how to **learn** these **mapping functions  $f$** ? Embeddings should keep the structure of the graph, and incorporate nodes' neighboring properties



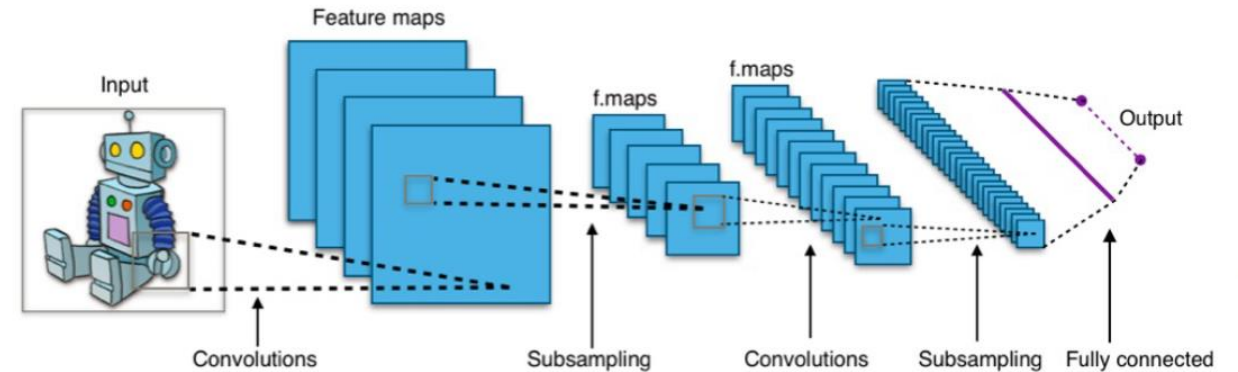
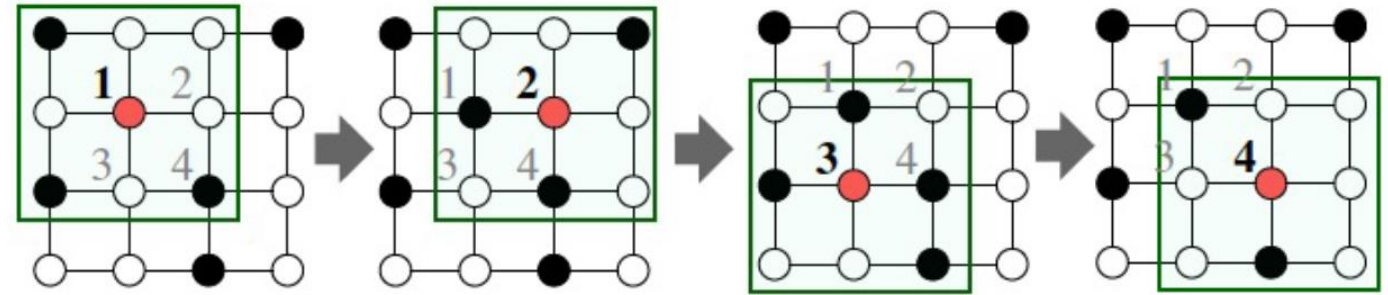
# Why not Traditional *Deep Learning*?

- *Deep Learning* is *designed* to specific, structured, *simple types of graphs*: *grids* and *sequences*
- Graphs have *no spatial locality as grids*
- *No fixed node ordering* as sequences

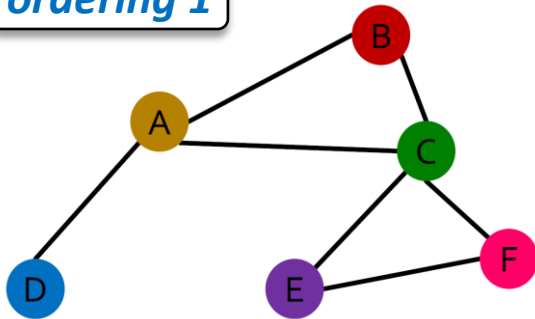


# Generalizing **Convolutions** to Graphs

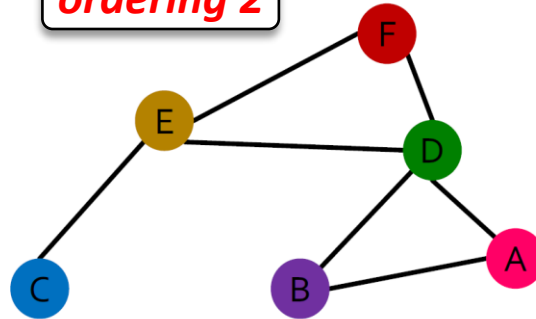
- **CNN on images:** convolution takes a little sub-patch of the image around a pixel (**node**) and **aggregates information** from its **neighbors** and **itself**
- The goal is to **generalize convolutions beyond simple lattices...**
- ...but as we said, there is **no fixed notion of locality** or sliding window **on the graph**
- And **graphs are permutation invariant!**



**ordering 1**



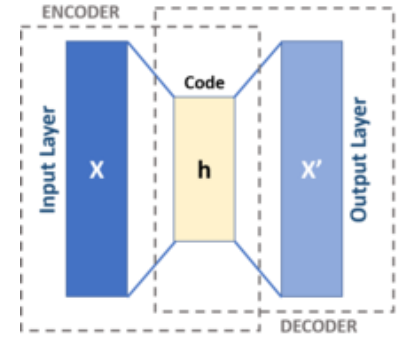
**ordering 2**



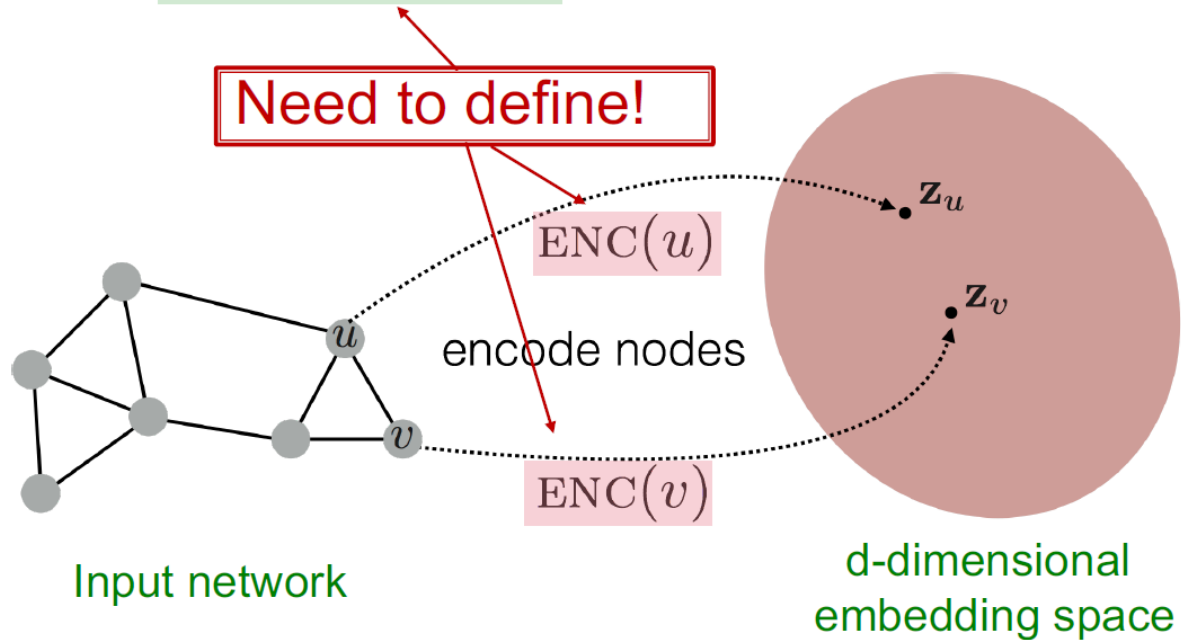
- Graphs **do not have a canonical order** of the nodes
- Graph and node **representations** should be the **same** for **ordering 1** and **ordering 2**

# Building the *Embeddings* – the *Encoding Function*

- **Recap:** GNNs basically consists in *encoding the graph* in the form of vectors and then using this encoding *to make predictions*
- **Encoder:** take a graph and *learn an embedding for every node of the graph*
- **Decoder:** use the learned embeddings and make predictions
- **Training:** feed embeddings into any loss function and run stochastic gradient descent to train weights



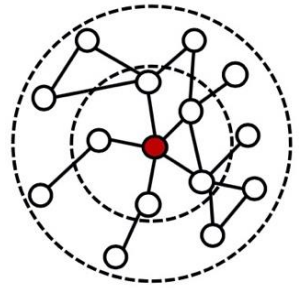
Goal:  $\text{similarity}(u, v) \approx \mathbf{z}_v^T \mathbf{z}_u$



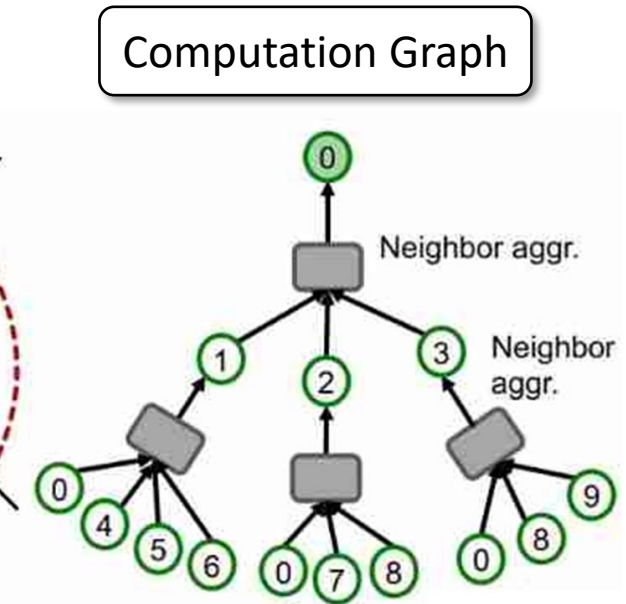
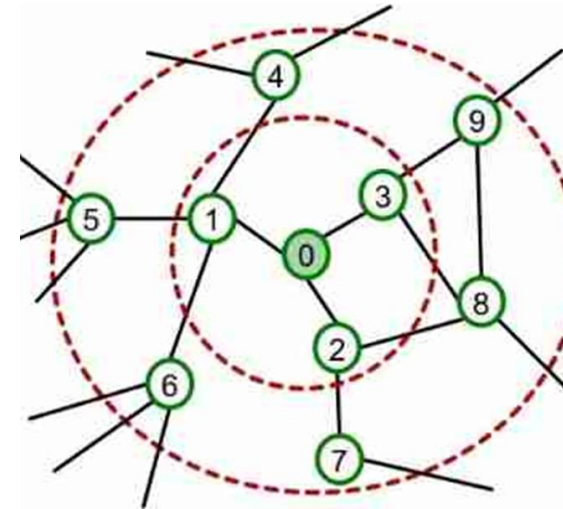
- let  $u$  and  $v$  be two nodes on the graph
- $x_u$  and  $x_v$  their corresponding node feature vectors
- the *encoding function*  $\text{ENC}(u)$  y  $\text{ENC}(v)$  convert the feature vectors to  $z_u$  and  $z_v$  in the embedding space
- the *decoding function* is simply the similarity between nodes:  $\text{similarity}(u, v) \approx \mathbf{z}_v^T \cdot \mathbf{z}_u$
- **challenge** → come up with *the encoder function*



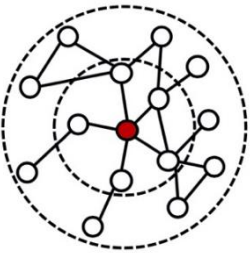
# Graph Convolutional Networks (GCNs)



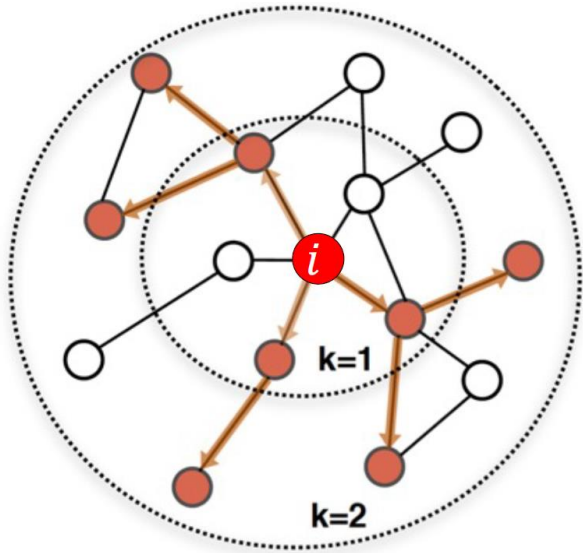
- For simplicity, let us consider a *simple type of GNN* – **Graph Convolutional Network (GCN)**
- We are looking for an encoder function which should be capable of:
  - **Integrating locality information** (local graph neighborhoods)
  - **Aggregating information**
  - **Stacking multiple layers** (computation) – deep graph encoders
- **Locality information** → the **neighborhood of a node** defines **a computation graph** (directed graph where nodes correspond to mathematical operations – acts as a **functional description of a computation**)
- **Key idea** → generate **node embeddings** based on local network neighborhoods.



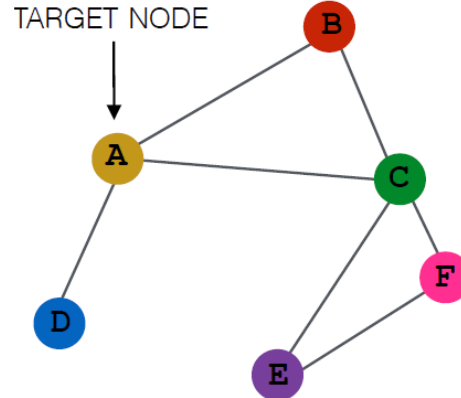
# Graph Convolutional Networks (GCNs)



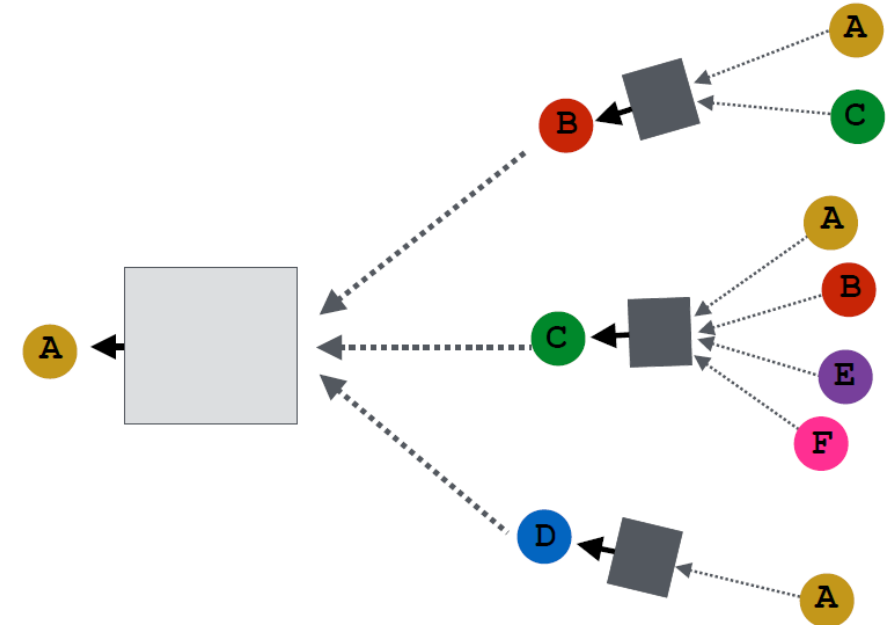
- **Key idea** → generate node embeddings based on local network neighborhoods ( $k$  hops), using **computation graphs**



$k$  hops for  
nearest neighbors



input graph  
embedding for **node A**



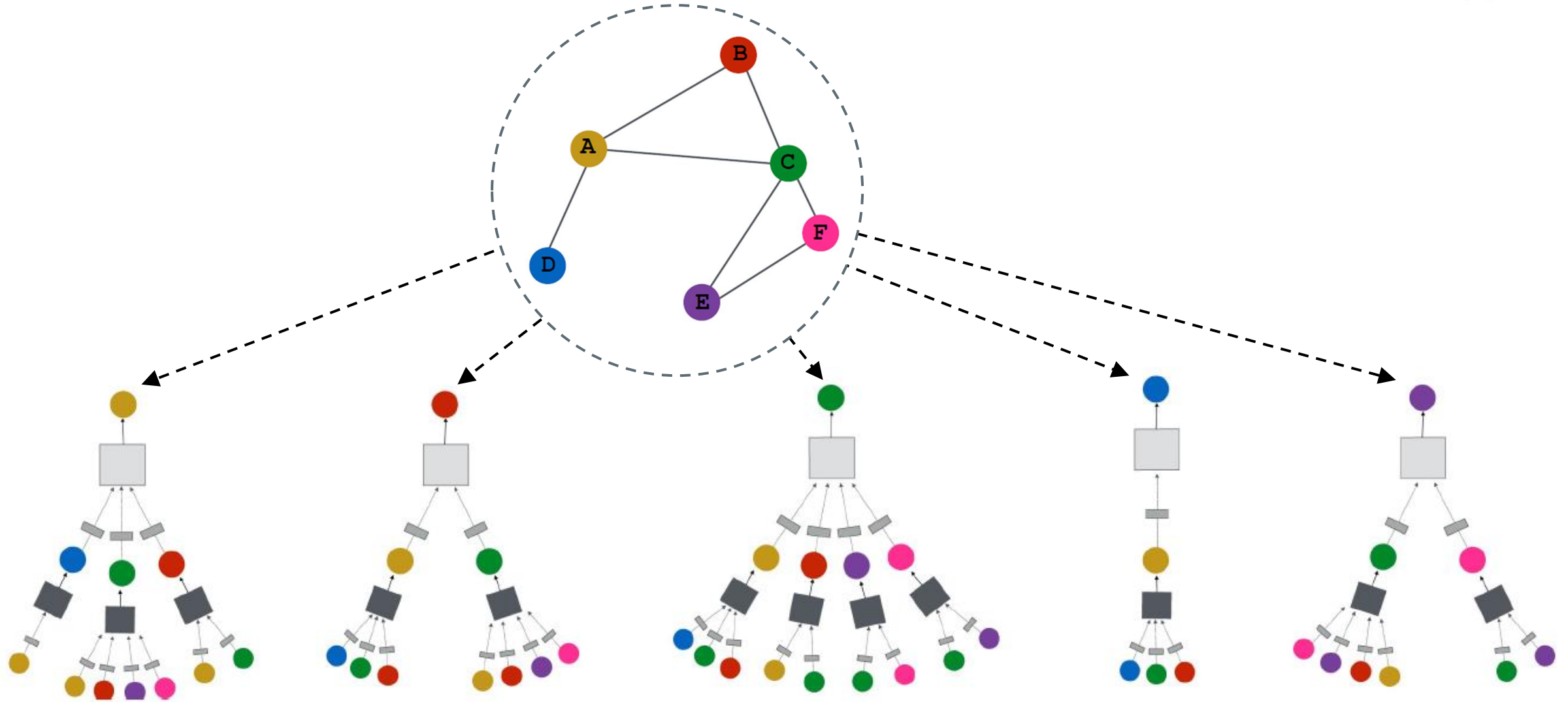
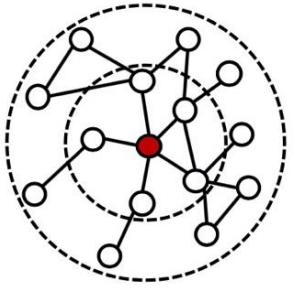
computation graph  
for **node A**

- Now that we have the **local information coded in a graph structure**, we do **data aggregation**

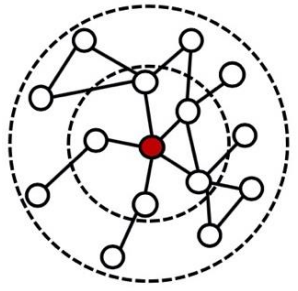


# Graph Convolutional Networks (GCNs)

- *Every node* defines a *computation graph* based on its neighborhood



# Neighborhood Aggregation with *Deep Encoders*

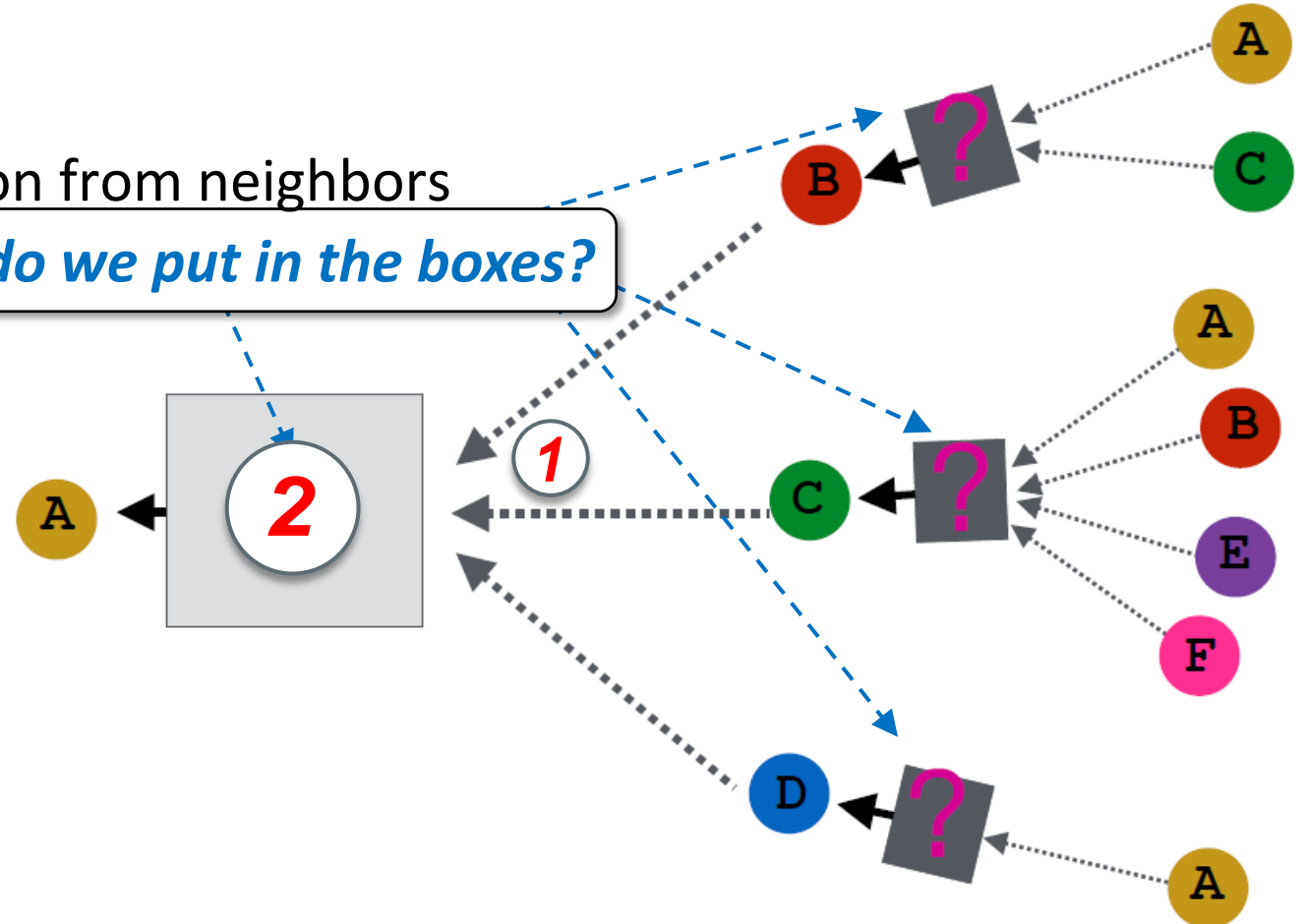


- Nodes aggregate information from their neighbors and apply *neural networks*

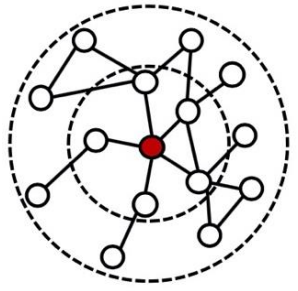
**(1) Basic aggregation:** average information from neighbors

*What do we put in the boxes?*

**(2) Apply neural network**



# Deep Encoders – Many Layers



- Model can be of **arbitrary depth** – depends on the  $k$  hops for NNs

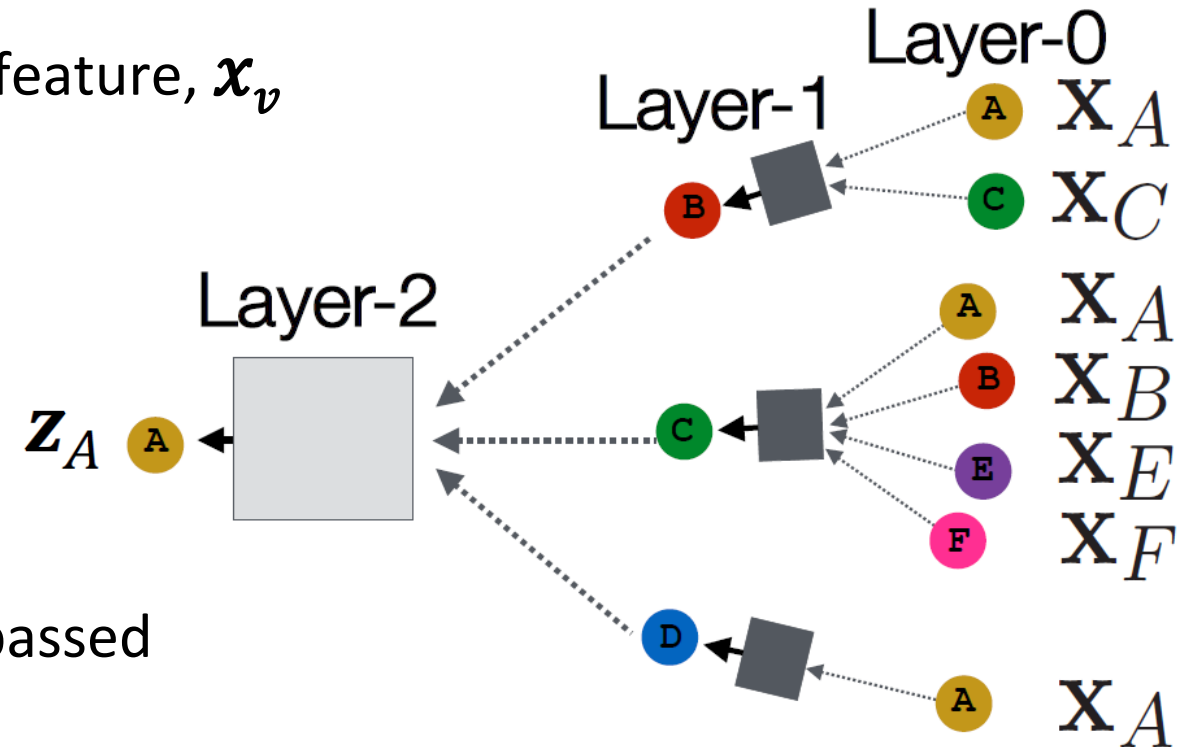
- Nodes ( $v$ ) have **embeddings at each layer  $k \rightarrow h_v^{(k)}$**

- Layer – 0 embedding of node  $v$  is its input feature,  $x_v$

- Layer –  $k$  embedding gets information from nodes that are  $k$  hops away

- Example:

- $x_A$  and  $x_C$  are the inputs at Layer-0
- Both feature vectors are aggregated and passed through an activation function in Layer-1
- And then passed to the next Layer-2



# Formulation of the *Deep Encoder*

$$\mathbf{h}_v^0 = \mathbf{x}_v \quad \leftarrow \text{initial layer 0 embeddings are equal to node features}$$

$$\mathbf{h}_v^k = \sigma \left( \mathbf{W}_k \sum_{u \in N(v)} \frac{\mathbf{h}_u^{k-1}}{|N(v)|} + \mathbf{B}_k \mathbf{h}_v^{k-1} \right), \quad \forall k > 0$$

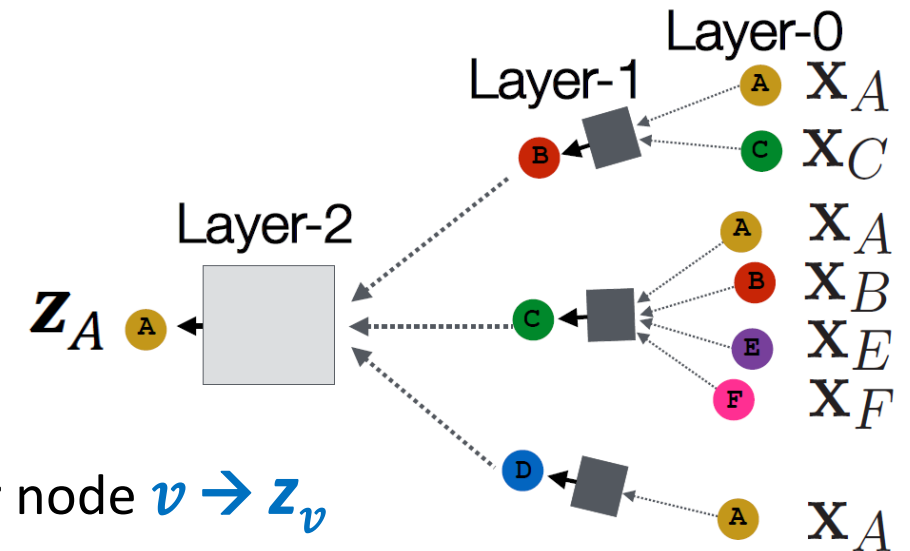
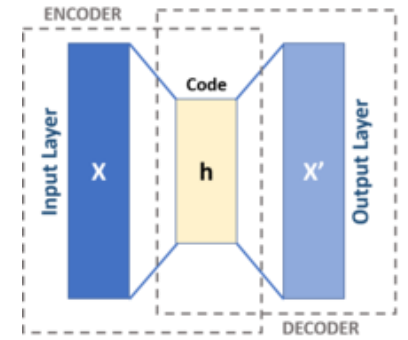
$\mathbf{h}_v^k$ :  $k^{\text{th}}$  layer embedding of  $v$   
 $\sigma$ : non-linearity  
 $\sum_{u \in N(v)} \frac{\mathbf{h}_u^{k-1}}{|N(v)|}$ : average of neighbor's previous layer embeddings  
 $\mathbf{h}_v^{k-1}$ : previous layer embedding of  $v$

$$\mathbf{z}_v = \mathbf{h}_v^{\text{last}}$$

$$k \in \{1, \dots, K\}$$

total number of layers

- Initial Layer-0 embeddings are equal to node features
- $N(v)$  is the set of neighboring nodes (embeddings)
- Non-linearity (**activation function**)  $\sigma \rightarrow$  e.g., ReLU
- Matrices  $\mathbf{W}_k$  and  $\mathbf{B}_k$  are the **trainable weights**
- After  $K$  layers of aggregation, we obtain the embedding for node  $v \rightarrow \mathbf{z}_v$



# Training the Model to *Generate Embeddings*

- To train the model (parameters), we need to define a *loss function on the embeddings*
- We can feed the embeddings into any loss function and run *SGD* to train the weights
- Training can be *supervised* or *unsupervised*
- *Supervised*: train model for supervised task, e.g., node classification, using *node labels  $y$*

$$\min_{\Theta} \mathcal{L}(y, f(z_v))$$

node embeddings

e.g., *L2 norm* if  $y$  are real numbers, *Cross Entropy (CE)* for categorical  $y$

- *Unsupervised* → use graph structure as supervision: similar nodes have similar embeddings
  - Unsupervised loss function can be a loss based on node proximity in the graph

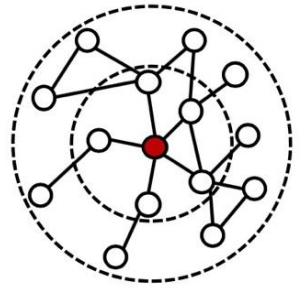
$$\mathcal{L} = \sum_{z_u, z_v} \text{CE}(y_{u,v}, \text{DEC}(z_u, z_v))$$

decoder (e.g., inner product)

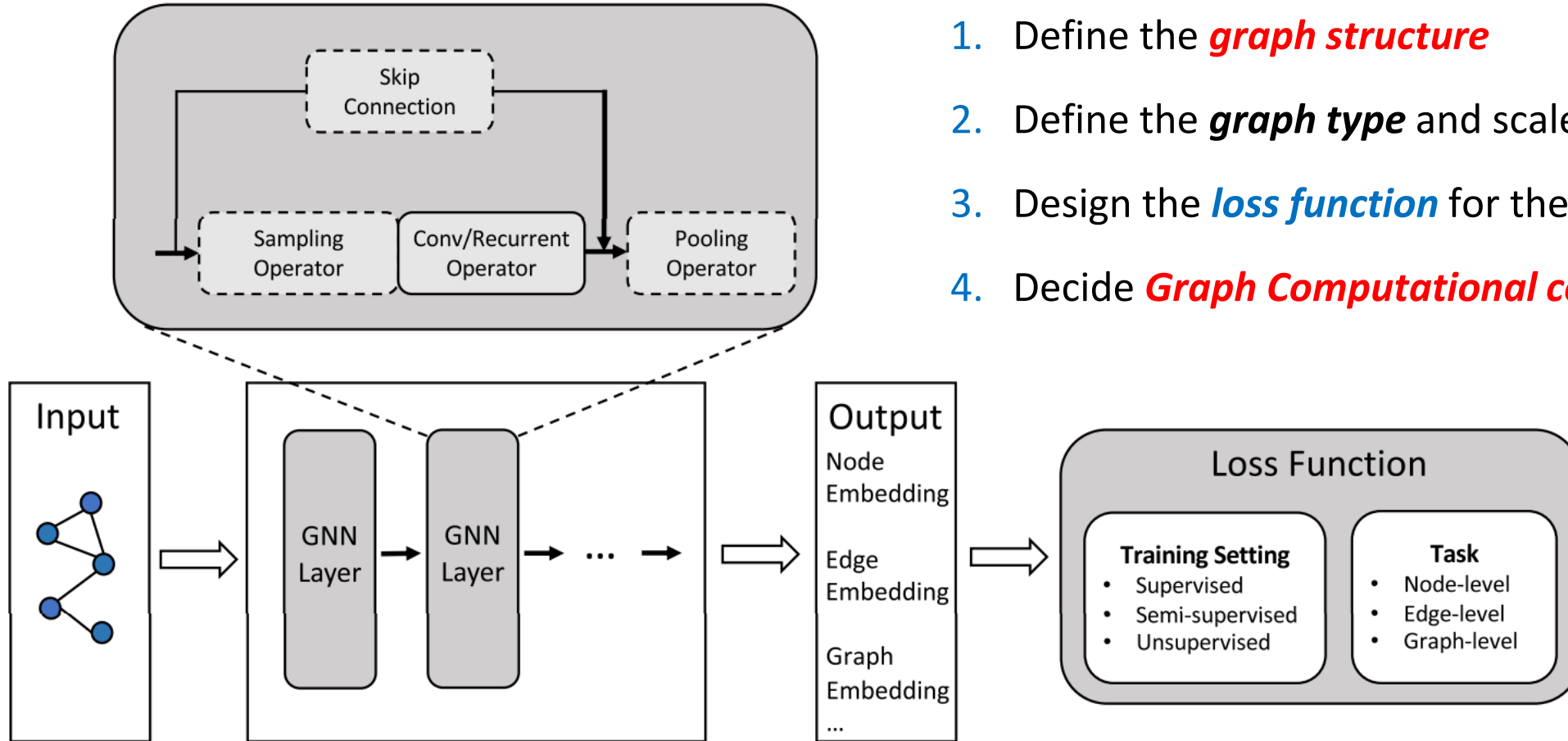
node similarity function



# GNN Design – Just the Tip of the Iceberg



- Many decisions and options to choose from when designing a GNN



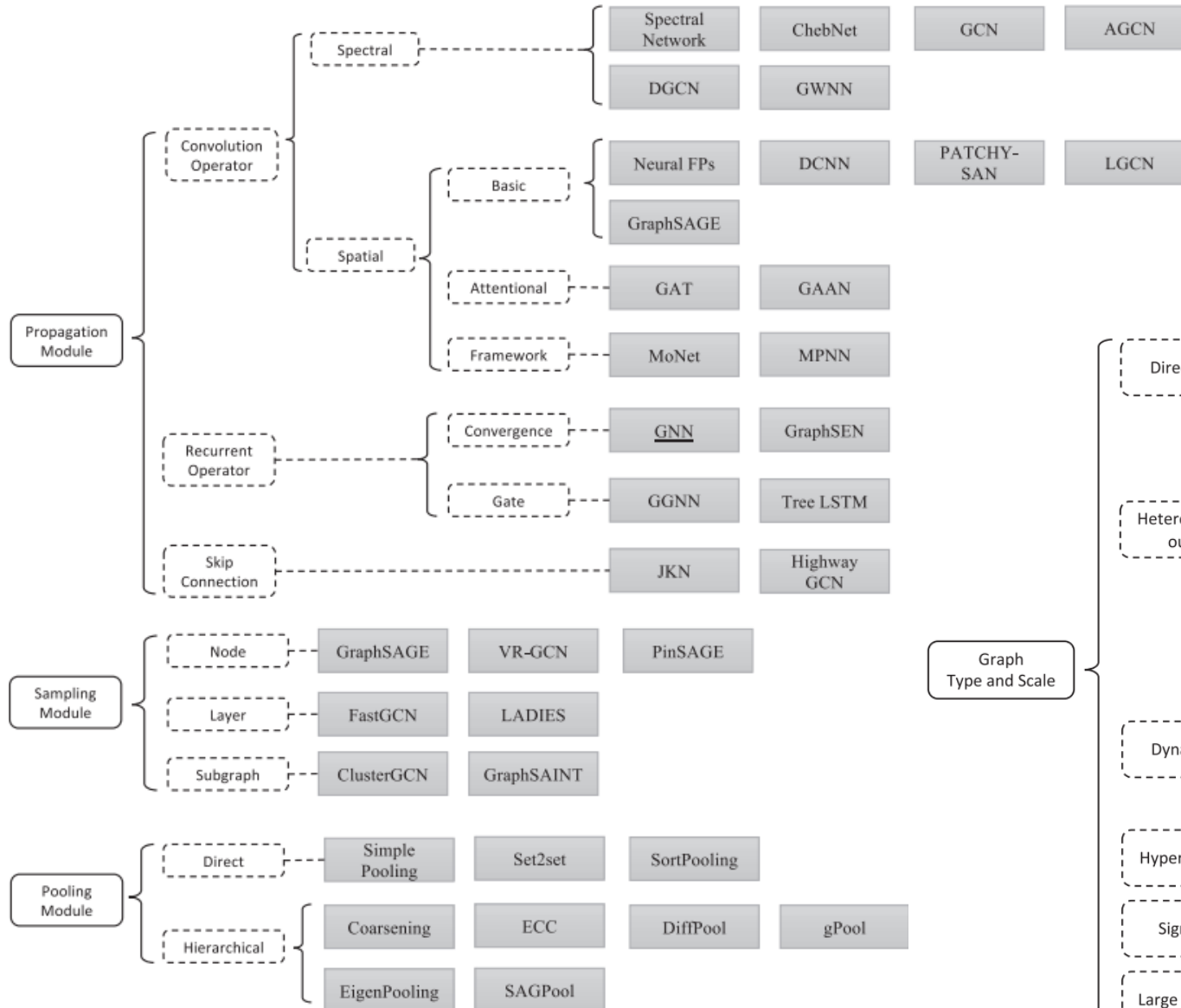
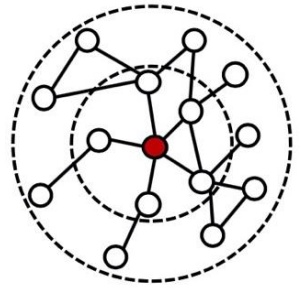
1. Find graph structure.

2. Specify graph type and scale.

4. Build model using computational modules.

3. Design loss function.

# GNN Design – Computational Components

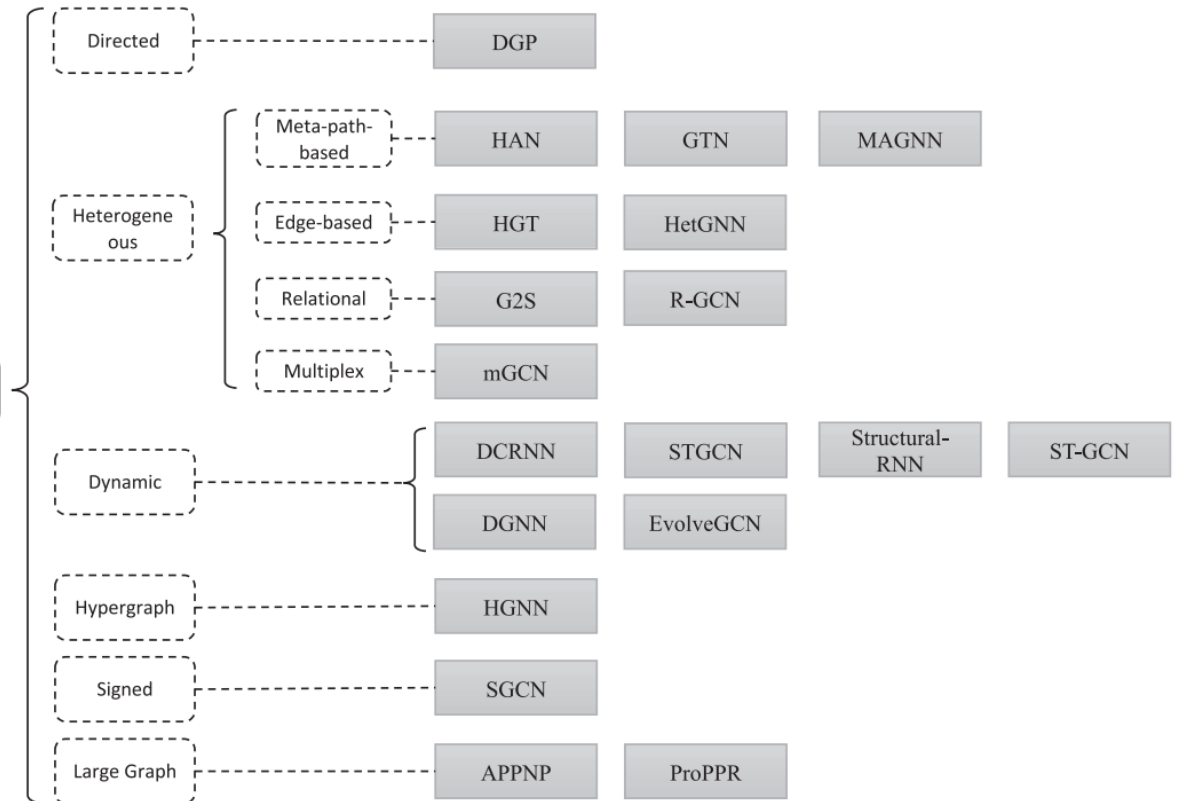


■ **Propagation modules**

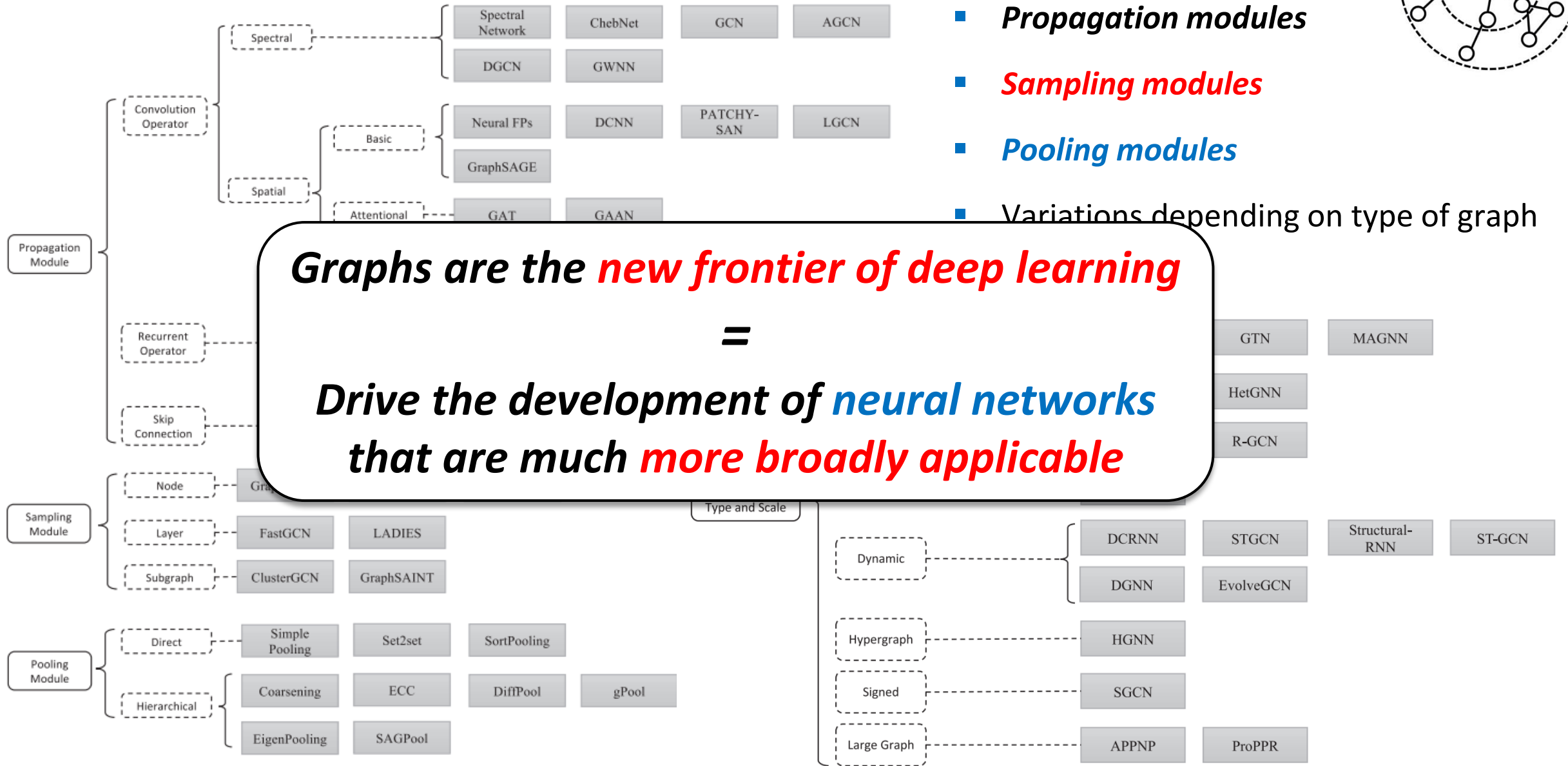
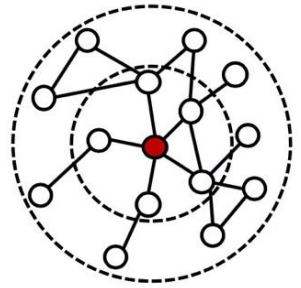
■ **Sampling modules**

■ **Pooling modules**

■ Variations depending on type of graph



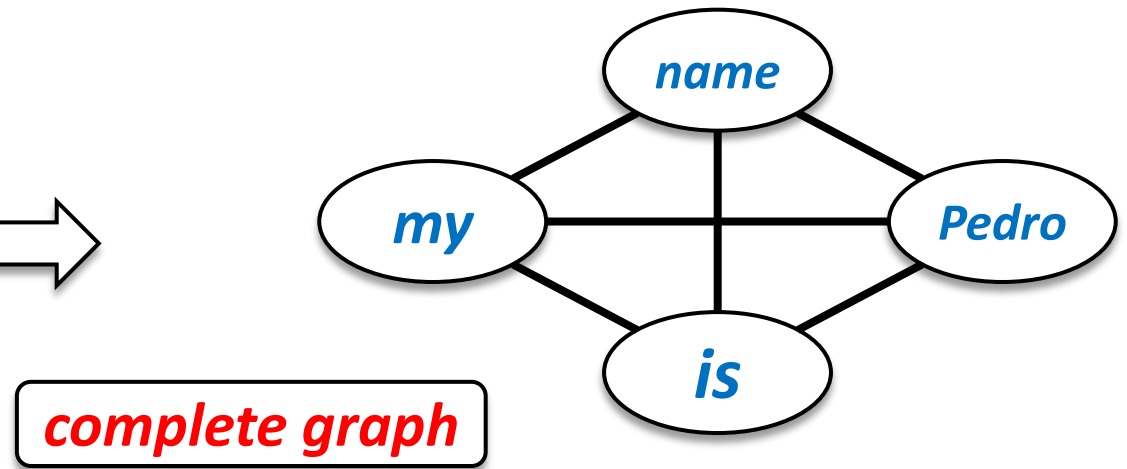
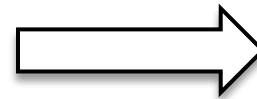
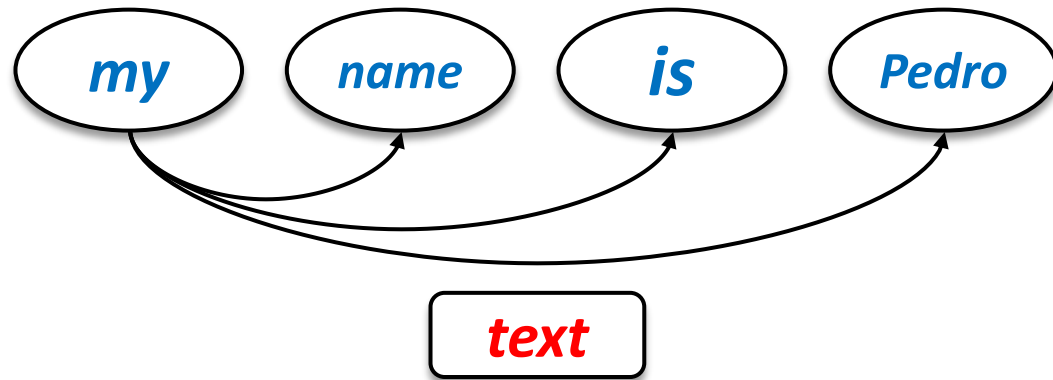
# GNN Design – Computational Components



# ***GNN*** vs ***CNN*** vs ***Transformers***



- **Recap: CNNs** can be seen as a **special GNN with fixed neighbor size and ordering**:
  - The size of the filter is pre-defined for a CNN
  - The advantage of GNN is it processes arbitrary graphs
  - CNNs are NOT permutation equivariant → switching the order of pixels will leads to different outputs
- **Transformers**: the most popular architecture to handle sequential data (text)
  - **Fully rely on self-attention**: every token (word) attends to all the other tokens via matrix calculation



# GNN vs CNN vs Transformers



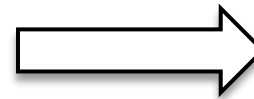
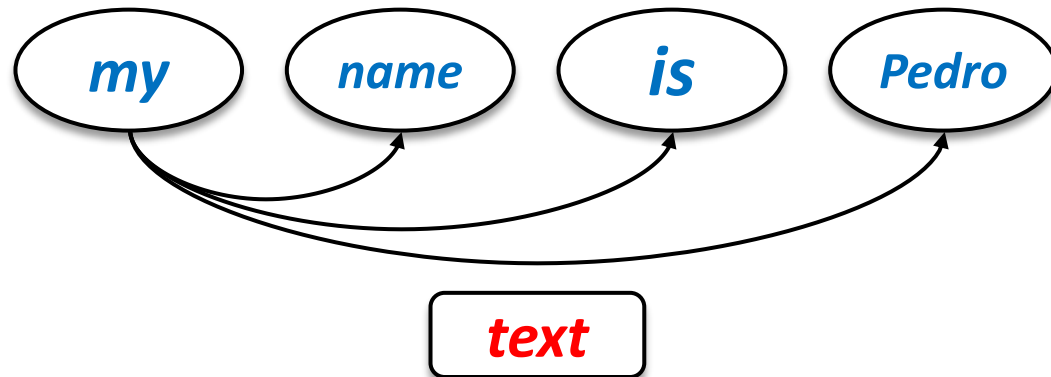
- **Recap: CNNs** can be seen as a **special GNN with fixed neighbor size and ordering**:

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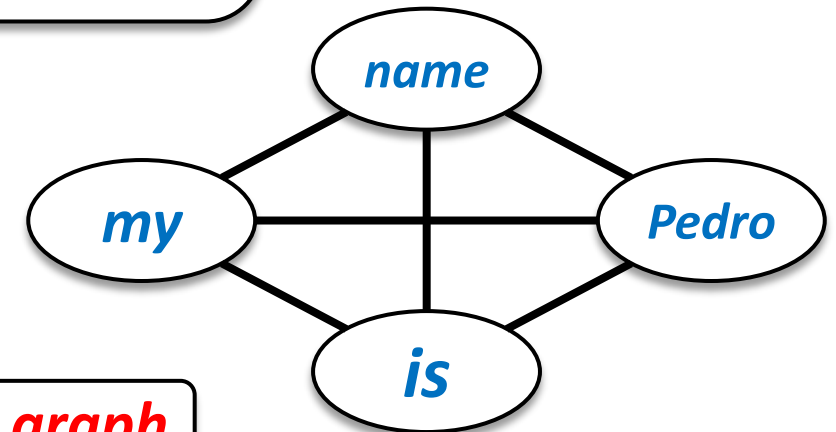
- **Transformers:**

- **Fully rely on**  
via matrix ca

**Transformer layer can be seen as a  
special GNN that runs on a fully-connected  
“word” graph**



**complete graph**





## CoNEXT 2022

- **Networks are graphs** 😊...the success of GNNs in recent years creates a great opportunity for a wide range of networking problems
- **GNNet** targets the **application of Graph Neural Network** (GNN) technology to **networking problems**
- Help building a strong community among those of us interested in what GNN can bring to networking
- Include a Special Session featuring the **best solutions** from the **BNN-UBP GNNet challenge 2022**



**Albert Cabellos**



**Pere Barlet-Ros**



**Franco Scarselli**



**Pedro Casas**

***Thanks***

**Dr. Pedro Casas**  
**Data Science & Artificial Intelligence**  
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